

GLAST collaboration meeting, UCSC June 22-24 1999

#### **GLAST tracking reconstruction**

**Status Report** 



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Outlook



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#### The picture of the GLAST tracker reconstruction

- The tree Dimensional Pair Fit
- Preliminary Results

The importance of being a Vertex Detector

- Fine pitch and Event Topologies
- Vertex Reconstruction



# Tracking Reconstruction

#### **Tracker Reconstruction:**

Using the: Tracker Recon **Silicon Hits** Energy measured in the Calorimeter Pattern Recongnition Should reconstruct that trajectory of the charged particles traversing the detector. Silicon Clusters Track Fitting Should estimate: Position and direction of the particles. Calorimeter Information Covariance matrices Gamma Energy (?) **Additional Tracks** and should provide: Direction Quality Criteria of the reconstructed tracks. Position CovarianceMatrix Extrapolation to subdetectors Energy Quality Critera

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# **Tracking Reconstruction Scheme**

#### The Physics inputs:

• Different range of Multiple Scattering

Main parameter:

#### pitch/distance

Different ranges of Energy (1GeV)

• Fitting electrons

The emission of bremsstralung photons

#### 5% of electron energy by plane

The initial part of the electromagnetic cascade!

• Reconstructing the gamma

The definition of the gamma using electron/positron tracks

Unknown track energies



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# Driver of the Tracking Reconstruction





## Pattern Recognition

#### **Pattern Recognition - Toolkit of Tracking Classes** A family of related classes that can construct: A Track **A Pair Event** A 3D track A 3D Pair Event The idea: the Pattern Recognition should recognize the gamma signature: two tracks split from a common vertex or an initial segment. **The Pattern Recognition main elements:** • Uses a Ray (Vector + Direction) as an input seed Information from the Calorimeter and neighbor hits • The search is based in plane by plane basic step() function : depends on the Track Objects (Track or Pair) • The search is controlled by an unique parameter

*m\_sigmaCut* : maximum distance in standard deviations at which

a hit is located away from a prediction point

• All Tracking Classes provide a common output data

GFdata :









# Tracking simulations The Pair Fit

#### Pattern Recognition - Pair Fit

- A "pair" tracks is created when:
  - A second segment can be constructed in the vicinity of N-first hits of the "best" track.
- *Step()* function propagates both tracks into the same plane
- The tracks do a competition for hits:
  - selfish or generous criteria?: (selfish of course!)

#### The 3D Pair Fit

- 3D "loose" connection :
  - A check is perform to guaranty that X-Y Si clusters of a connected track are in the same tower
- The 3D pair are ambiguous (4 X-Y combinations) unless:
  - Topological identification (hard)
    - One track crosses to a neighbor tower
    - One track stops
  - Energy criteria (soft)
    - Connection of the "best" tracks in both projection



The 3D pair Fit reconstruction of a gamma event

• Versatility: (The 3D identification (combinatory or topology) is a free parameter)

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# Tracking simulations Tracking Reconstruction Classes Organization





# Example of a reconstructed gamma



The projection and 3D view of a reconstructed gamma event

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# Tracking Fitting procedure: The Kalman Filter



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# An example of a reconstructed cosmic event

Reconstruction of cosmic Background - protons





# Tracking efficiencies

#### Tracking Efficiency:

- 95% for angles ? < 45 deg
- 80% for angles ? < 80 deg
- almost flat with energy



- ~80% for angles ? < 80 deg
- Almost invariant with energy and incident angle.



Tracker Efficiency Reconstruction for gammas



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#### Angular distributions

Angular distributions for gamma 30 degrees incident angle in X direction



![](_page_13_Picture_0.jpeg)

### PSF and Effective area

2D pair reconstruction results - current repository

![](_page_13_Figure_4.jpeg)

![](_page_14_Picture_0.jpeg)

# Status and Future plans

#### **Status of the Tracking Reconstruction :**

- The tracker reconstruction works for AO purposes.
- The Pair-Fit reconstruction should be tuned up, understood and it potential explored.
- The actual reconstruction works a strong framework for further improvements and additions.

#### But, there is still a lot of work to do:

- PSF Studies based on topological criteria.
- Studies of low energy gamma (PSF and the addition of the electron/positron tracks).
- Understanding the Pair-Fit efficiency and causes of tracking failures.
- Estimation of the energy using the tracker information.
- Tracks extrapolation to other subdetectors.
- Background rejection based on topological criteria

# <sup>•</sup>The tracking reconstruction and the background rejection

#### The Background rejection variables: (surplus\_hit\_ratio, csi\_err\_nrm, etc)

- They contain a relevant part of the legacy of Bill Atwood's great work.
- For historical reasons they were calculated (most of them) in TrackerRecon
- They combine tracker/ACD/Calorimeter information and they are used for background rejection.
- They have been broken with the new-reconstruction but nobody has paid attention to them.
- And the A0 is almost there.

#### **Proposal:**

• Lets not panic! (yet)

• There are only some decens of lines of code that we should be able to understand and corrected it (it would maybe require the collaboration of people working in reconstruction and background rejection).

#### **Status:**

- After Bill's fix last Thursday (two lines of code), they almost look OK.
- The main variable broken is csi\_corrected\_energy.

#### For the future (not for the AO):

• The GlastSim output is a Ntuple that is not convenient for analysis that relies on fundamental reconstruction parameters.

• In order to be able to perform an effective background rejection analysis, as well as other studies: (I.e. efficiencies ) we need a reconstruction output similar to most HEP experiments (I.e. list of track and its extrapolation to ACD and calorimeter)

• As the panel recommended.

![](_page_16_Picture_0.jpeg)

# Pair Fit reconstruction use: Background rejection

![](_page_16_Figure_3.jpeg)

![](_page_17_Picture_0.jpeg)

# The importance of being a Vertex detector

![](_page_17_Figure_3.jpeg)

#### The PSF depends on the event topology

• Classification depending on the number of hits in the initial Vertex,

Atwood's first\_hit\_count variable

• How important is determinate the initial vertex and the cracks.

An example with 100 MeV, normal incident gammas

• The impact in the aspect ratio of GLAST

![](_page_18_Picture_0.jpeg)

# First Hit Count - Topologies

![](_page_18_Figure_3.jpeg)

![](_page_19_Picture_0.jpeg)

### First Hit Count - Topologies

X Slope 100 MeV, normal incident angle, for the different topologies

![](_page_19_Figure_4.jpeg)

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![](_page_20_Picture_0.jpeg)

### Vertex Determination Studies

X slope distributions for the well reconstructed and erroneous vertexes

First Hit Count and Active Distance for well reconstructed and erroneous vertexes

![](_page_20_Figure_5.jpeg)

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![](_page_21_Picture_0.jpeg)

### **Vertex Determination Studies**

Active Distance and distance to the tower boundary for the well reconstructed and erroneous vertexes after the cut on *first hit count* 

MC position of the erroneous vertexes after the cut on first hit count

![](_page_21_Figure_5.jpeg)

![](_page_21_Figure_6.jpeg)

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![](_page_22_Picture_0.jpeg)

### Vertex determination studies

*First hit count* Cut efficiency as a function of energy and incident angle

![](_page_22_Figure_4.jpeg)

*First hit count* Cut enhancement as a function of energy and incident angle

![](_page_22_Figure_6.jpeg)

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![](_page_23_Picture_0.jpeg)

## **GLAST** acceptance

#### The aspect ratio (high/width) of GLAST

The main design parameter of the tracker is the ratio *pitch/gap* between planes
The smaller the pitch, the lower the distance between gaps.
That enhances the FoV and the acceptance of the Detector

![](_page_23_Figure_5.jpeg)

Tracking Efficiency Reconstruction (Baseline)

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![](_page_23_Figure_8.jpeg)

![](_page_23_Figure_9.jpeg)

![](_page_23_Figure_10.jpeg)

Tracking Efficiency (left) and Calorimeter (right) (SuperGLAST)

![](_page_24_Picture_0.jpeg)

# Conclusions

#### **The Pair Fit/Kalman Filter reconstruction**

- works in acceptable level for the A0 y it is very efficient.
- It serves as a solid framework for further developments.
- It a good approximation to our tracking reconstruction problem.
- It needs to be tune up, understood, and its potential explored.
- There are problems with analysis variables that need to be understood immediately.

#### **GLAST is a Vertex detector**

- The PSF (specially at low energies) depends on the event topology.
- In order to be able to separate and identify the different gamma conversion topologies, GLAST needs a precise determination of the interaction vertex
- Or in other words, GLAST should be a fine granularity (fine pitch) tracking detector.
- GLAST should accurate determinate the conversion vertex.

![](_page_25_Picture_0.jpeg)

### Angular distributions

Angular distributions for normal incident angles

![](_page_25_Figure_4.jpeg)

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