

# Physics 105. Mechanics. Professor Dine

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## Fall, 2004. Handout: The Central Field Problem

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These notes are meant as a supplement to the materials in chapter 8 of your textbook.

### 1 Lagrangian and Hamiltonian in Special Relativity

A guess:

$$S = -mc \int ds = -mc \int \sqrt{c^2 dt^2 - d\vec{x}^2} \quad (1)$$

$$= \int dt L$$

$$L = -mc^2 \sqrt{1 - \left(\frac{1}{c^2} \frac{d\vec{x}}{dt}\right)^2} \quad (2)$$

Note that for small velocities,

$$L = -mc^2 + \frac{1}{2} m \dot{x}_i^2 \quad (3)$$

so up to a constant, it is the lagrangian we have used for non-relativistic problems. Using the Hamiltonian construction, the momenta are:

$$p^i = \frac{\partial L}{\partial \dot{x}^i} = \frac{m \dot{x}^i}{\sqrt{1 - v^2/c^2}} \quad (4)$$

The Hamiltonian is:

$$\begin{aligned} H &= p^i \dot{x}^i - L \\ &= \frac{mv^2 + mc^2(1 - \frac{1}{c^2}v^2)}{\sqrt{1 - v^2/c^2}} \\ &= \frac{mc^2}{\sqrt{1 - v^2/c^2}} \end{aligned} \quad (5)$$

### 2 Pendulum with Lagrange Multipliers

$$L = \frac{1}{2} m (\dot{x}^2 + \dot{y}^2) + mgy - \lambda(x^2 + y^2 - \ell^2). \quad (6)$$

We can solve this by writing:  $x = \ell \sin(\theta)$ ;  $y = -\ell \cos(\theta)$ . But let's proceed with the lagrange multipliers. The equations of motion for  $x$  and  $y$  are:

$$m\ddot{x} + 2\lambda x = 0; m\ddot{y} - mg + 2\lambda y = 0. \quad (7)$$

The variation with respect to  $\lambda$  gives the constraint:

$$x^2 + y^2 - \ell^2 = 0. \quad (8)$$

Differentiating twice gives:

$$\ddot{x}x + \ddot{y}y + \dot{x}^2 + \dot{y}^2 = 0. \quad (9)$$

We can substitute this in the equations for  $x$  and  $y$ . In particular, if we take the first equation, and multiply by  $y$ , and the second and multiply by  $x$  and add, we get:

$$m(x\ddot{x} + y\ddot{y}) + 2\lambda(x^2 + y^2) + mgy = 0. \quad (10)$$

Using the constraint equation, we can eliminate the first term, and solve for  $\lambda$ :

$$\lambda = \frac{-mgy + m(\dot{x}^2 + \dot{y}^2)}{2(x^2 + y^2)}. \quad (11)$$

This is, in fact, the tension in the rod. If you substitute back, e.g., in the  $x$  equation, you see the force  $T_x$ .

$$m\ddot{x} - \frac{mgxy}{x^2 + y^2} + \frac{m(\dot{x}^2 + \dot{y}^2)x}{(x^2 + y^2)} \quad (12)$$

i.e.  $T_x = -T \sin(\theta)$  and similarly for  $y$ .