Physics 217 Winter 2018

The Addition Theorem of Spherical Harmonics

The addition theorem for spherical harmonics states that

$$P_{\ell}(\cos \theta) = \frac{4\pi}{2\ell + 1} \sum_{m=-\ell}^{\ell} Y_{\ell m}(\hat{\boldsymbol{n}}') Y_{\ell m}^{*}(\hat{\boldsymbol{n}}''), \quad \text{where } \cos \theta \equiv \hat{\boldsymbol{n}}' \cdot \hat{\boldsymbol{n}}''.$$
(1)

The standard proof of this theorem can be found on pp. 110–111 of John David Jackson, *Classical Electrodynamics*, 3rd Edition (John Wiley & Sons, Inc., Hoboken, NJ, 1999). In this note, I shall provide an alternative proof that makes use of the theory of angular momentum operators in quantum mechanics.

An (actively) rotated state vector, corresponding to a state with no internal spin degrees of freedom, is denoted by

$$|\psi\rangle_R \equiv U[R]|\psi\rangle\,,\tag{2}$$

where $R \equiv R(\chi \hat{\boldsymbol{u}})$ is a counterclockwise rotation by an angle χ about a fixed axis along the unit vector $\hat{\boldsymbol{u}}$, and $U[R] = e^{-i\chi \hat{\boldsymbol{u}} \cdot \vec{\boldsymbol{L}}/\hbar}$ is the corresponding unitary operator that acts on quantum states of the Hilbert space. Likewise, the coordinate basis ket $|\vec{\boldsymbol{x}}\rangle$ can also be rotated,

$$|\vec{x}'\rangle = U[R]|\vec{x}\rangle, \quad \text{where } \vec{x}' = R\vec{x}.$$
 (3)

We also define unit vectors, $\hat{\boldsymbol{n}} \equiv \vec{\boldsymbol{x}}/|\vec{\boldsymbol{x}}|$ and $\hat{\boldsymbol{n}}' \equiv \vec{\boldsymbol{x}}'/|\vec{\boldsymbol{x}}'|$, where $\hat{\boldsymbol{n}}' = R\hat{\boldsymbol{n}}$. With respect to a fixed z-axis, $\hat{\boldsymbol{n}}$ points in a direction with polar angle θ and azimuthal angle ϕ , and $\hat{\boldsymbol{n}}'$ points in a direction with polar angle θ' and azimuthal angle ϕ' .

Since U[R] is a unitary operator, we can write,

$$\psi(\vec{\boldsymbol{x}}) = \langle \vec{\boldsymbol{x}} | \psi \rangle = \langle \vec{\boldsymbol{x}} | U^{\dagger}[R] U[R] | \psi \rangle = \langle \vec{\boldsymbol{x}'} | \psi \rangle_R = \psi_R(\vec{\boldsymbol{x}'}),$$

after employing eqs. (2) and (3). That is,¹

$$\psi_R(\vec{x}') = \psi(\vec{x}) = \psi(R^{-1}\vec{x}'). \tag{4}$$

Consider the state vector $|\psi\rangle = |\ell m\rangle$, which is a simultaneous eigenstate of \vec{L}^2 and L_z with corresponding eigenvalues $\hbar^2 \ell(\ell+1)$ and $\hbar m$, respectively. Then, using eq. (2),

$$\psi_{R}(\vec{\boldsymbol{x}'}) = \langle \vec{\boldsymbol{x}'} | \psi \rangle_{R} = \langle \vec{\boldsymbol{x}'} | U[R] | \ell m \rangle = \sum_{\ell=0}^{\infty} \sum_{m'=-\ell'}^{\ell'} \langle \vec{\boldsymbol{x}'} | \ell' m' \rangle \langle \ell' m' | U[R] | \ell m \rangle.$$
 (5)

Note that $D_{m'm}^{(\ell)}(R) \, \delta_{\ell\ell'} \equiv \langle \ell' \, m' | \, U[R] \, | \, \ell \, m \rangle$, since $[\vec{\boldsymbol{L}}, L_i] = 0$ implies that the matrix elements of $\vec{\boldsymbol{L}}$ (as well as any function of $\vec{\boldsymbol{L}}$) are diagonal in ℓ . In addition, $Y_{\ell'm'}(\hat{\boldsymbol{n'}}) = \langle \vec{\boldsymbol{x'}} | \, \ell' \, m' \rangle$. Hence, eq. (5) yields

$$\psi_R(\vec{\boldsymbol{x}'}) = \sum_{m'=-\ell}^{\ell} Y_{\ell m'}(\hat{\boldsymbol{n}'}) D_{m'm}^{(\ell)}[R].$$
(6)

¹Since eq. (4) is true for any \vec{x}' (which can be treated as a dummy variable), we are free to drop the prime superscript and write $\psi_R(\vec{x}) = \psi(R^{-1}\vec{x})$.

²Since θ' and ϕ' are the polar and azimuthal angles of the unit vector $\hat{\boldsymbol{n}}'$, we denote $Y_{\ell'm'}(\hat{\boldsymbol{n}}') \equiv Y_{\ell'm'}(\theta',\phi')$.

In light of eq. (4), $\psi_R(\vec{x}') = \psi(\vec{x}) = \langle \vec{x} | \ell m \rangle = Y_{\ell m}(\hat{n})$. Hence, eq. (6) yields,

$$Y_{\ell m}(\hat{\boldsymbol{n}}) = \sum_{m'=-\ell}^{\ell} Y_{\ell m'}(\hat{\boldsymbol{n}}') D_{m'm}^{(\ell)}[R], \quad \text{where } \hat{\boldsymbol{n}}' = R\hat{\boldsymbol{n}}.$$
 (7)

Note that an equivalent method for deriving eq. (7) starts from the observation that if $\hat{\boldsymbol{n}}' = R\hat{\boldsymbol{n}}$, then $|\hat{\boldsymbol{n}}'\rangle = U[R]|\hat{\boldsymbol{n}}\rangle$. It then follows that

$$\langle \hat{\boldsymbol{n}}' | = \langle \hat{\boldsymbol{n}} | U^{\dagger} [R] . \tag{8}$$

Since U[R] is a unitary operator, we can write,

$$\langle \hat{\boldsymbol{n}} \mid \ell \, m \rangle = \langle \hat{\boldsymbol{n}} \mid U^{\dagger}[R] \, U[R] \mid \ell \, m \rangle = \langle \hat{\boldsymbol{n}'} \mid U[R] \mid \ell \, m \rangle = \sum_{\ell=0}^{\infty} \sum_{m'=-\ell'}^{\ell'} \langle \hat{\boldsymbol{n}'} \mid \ell' \, m' \rangle \langle \ell' \, m' \mid U[R] \mid \ell \, m \rangle$$

$$=\sum_{\ell=0}^{\infty}\sum_{m'=-\ell'}^{\ell'}\langle\hat{\boldsymbol{n}'}\mid\ell'\,m'\rangle\,D_{m'm}^{(\ell)}[R]\,\delta_{\ell\ell'}=\sum_{m'=-\ell}^{\ell}\langle\hat{\boldsymbol{n}'}\mid\ell\,m'\rangle\,D_{m'm}^{(\ell)}[R]\,,$$

which is equivalent to eq. (7).

The z axis points along the unit vector $\hat{\boldsymbol{z}}$. Given the rotation R that appears in eq. (7), we define a unit vector $\hat{\boldsymbol{n}}'' \equiv R\hat{\boldsymbol{z}}$. If the rotation $R = R(\alpha, \beta, \gamma)$ is parameterized by its Euler angles, α , β , γ , then $R(\alpha, \beta, \gamma) = R(\alpha \hat{\boldsymbol{z}})R(\beta \hat{\boldsymbol{y}})R(\gamma \hat{\boldsymbol{z}})$, where the three rotations are applied from right to left. Note that the direction of $\hat{\boldsymbol{n}}''$ does not depend on γ , since $R(\gamma \hat{\boldsymbol{z}})\hat{\boldsymbol{z}} = \hat{\boldsymbol{z}}$. Hence, $\hat{\boldsymbol{n}}'' = R(\alpha, \beta, \gamma)\hat{\boldsymbol{z}} = R(\alpha \hat{\boldsymbol{z}})R(\beta \hat{\boldsymbol{y}})\hat{\boldsymbol{z}}$. That is, the unit vector $\hat{\boldsymbol{n}}''$ has polar angle β and azimuthal angle α with respect to the z-axis.

To obtain the addition theorem for spherical harmonics, we set m = 0 in eq. (7) and use the identities,³

$$Y_{\ell 0}(\hat{\boldsymbol{n}}) = \sqrt{\frac{2\ell+1}{4\pi}} P_{\ell}(\cos\theta), \qquad (9)$$

$$D_{m'0}^{(\ell)}(\alpha,\beta,\gamma) = \sqrt{\frac{4\pi}{2\ell+1}} Y_{\ell m'}^*(\hat{\boldsymbol{n}''}), \qquad (10)$$

where θ is the polar angle of \hat{n} with respect to the z-axis. It then immediately follows that

$$P_{\ell}(\cos \theta) = \frac{4\pi}{2\ell + 1} \sum_{m=-\ell}^{\ell} Y_{\ell m}(\hat{\boldsymbol{n}}') Y_{\ell m}^{*}(\hat{\boldsymbol{n}}'').$$

$$\tag{11}$$

after relabeling m' with m. Finally, we use $\hat{\boldsymbol{n}}' = R\hat{\boldsymbol{n}}$ and $\hat{\boldsymbol{n}}'' = R\hat{\boldsymbol{z}}$ to obtain,

$$\hat{\boldsymbol{n}}' \cdot \hat{\boldsymbol{n}}'' = (R_{ij}n_j)(R_{ik}z_k) = \delta_{jk}n_j z_k = \hat{\boldsymbol{n}} \cdot \hat{\boldsymbol{z}} = \cos\theta.$$
(12)

Hence, we have reproduced the addition theorem of spherical harmonics given in eq. (1).

³A proof of eq. (10) appears in Appendix C of the class handout entitled, *Clebsch-Gordan coefficients and the tensor spherical harmonics*.

⁴In eq. (12), there is an implicit sum over the repeated indices. Since the rotation matrix R is orthogonal, it follows that $R_{ij}R_{ik} = R_{ji}^{\mathsf{T}}R_{ik} = (R^{\mathsf{T}}R)_{jk} = \delta_{jk}$.